

Algebraic Tools for TDA in a Multiparameter Setting

based on joint work with Wojciech Chachólski and René Corbet

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Topological Data Analysis

Studying the shape of data...

...with tools from (algebraic) topology

Applications

- ◇ medical and life sciences
- ◇ distinguishing point processes on a unit square (Chachólski–Riihimäki, 2020)
- ◇ topological machine learning

... **whenever data arise!**

Behind the scenes

- ◇ commutative algebra
- ◇ algebraic geometry

New invariants of multigraded modules...

... arising from TDA

Barcoding

Main tool: persistent homology

Associating barcodes to data

Input: point cloud $\{p_i\} \subseteq \mathbb{R}^N$

- 1 $X_\varepsilon := \cup_{p_i} B_\varepsilon(p_i)$
- 2 increase $\varepsilon \xrightarrow{\text{nerve}}$ filtered simplicial complex
- 3 for all n : n -th homology with coefficients in \mathbb{K} naturally is a finitely generated \mathbb{N} -graded module P_n over $\mathbb{K}[t]$
- 4 structure theorem for finitely generated modules over PIDs:

$$P_n \cong \bigoplus_i \mathbb{K}[t]t^{\alpha_i} \oplus \bigoplus_j \mathbb{K}[t]t^{\beta_j} / \mathbb{K}[t]t^{\beta_j + \gamma_j}$$

Output: barcode $\{[\alpha_i, \infty), [\beta_j, \beta_j + \gamma_j)\}$

Fact: This invariant is discrete, complete, and stable.

Multiparameter persistence

Study of **multifiltered** simplicial complexes (Carlsson–Zomorodian, 2009)

Algebraic counterpart

\mathbb{N}^r -graded $\mathbb{K}[x_1, \dots, x_r]$ -modules $M = \bigoplus_{a \in \mathbb{N}^r} M_a$

Challenges

- ◇ no higher-dimensional analogue of barcodes
- ◇ lack of **stable**, **algorithmic** invariants

Multipersistence modules as functors

Let $G \in \{\mathbb{N}^r, \mathbb{R}_{\geq 0}^r\}$ (more general monoids in (Corbet–Kerber, 2018))

$$\begin{array}{ccc} \text{Fun}((G, \leq), \text{Vect}_{\mathbb{K}}) & \xrightarrow{\text{isom. of cats}} & G\text{-graded } \mathbb{K}[G]\text{-modules} \\ \cup & \cong & \cup \\ \text{Tame}((G, \leq), \text{Vect}_{\mathbb{K}}) & \cong & \text{finitely presented } G\text{-graded } \mathbb{K}[G]\text{-modules} \end{array}$$

Turning discrete into stable invariants

T a set

f a discrete invariant $f: T \rightarrow \mathbb{N}$

d an extended pseudometric $d: T \times T \rightarrow \mathbb{R}_{\geq 0} \cup \{\infty\}$

\mathcal{M} measurable functions $[0, \infty) \rightarrow [0, \infty)$ endowed with interleaving distance

Definition & Theorem (Gäfvert–Chachólski, 2017)

The **hierarchical stabilization** of f at $x \in T$, denoted $\hat{f}(x) \in \mathcal{M}$, is

$$\hat{f}(x)(\tau) := \min \{f(y) \mid y \in T: d(x, y) \leq \tau\}.$$

For any choice of d , $\hat{f}: T \rightarrow \mathcal{M}$ is 1-Lipschitz.

Measuring distances between tame functors

How to construct metrics—in best case in a way that is suitable for learning tasks?

Pseudometrics arising from contours

\mathbf{R}_∞^r the poset obtained from adding one element ∞ to $\mathbb{R}_{\geq 0}^r$

Definition

A **persistence contour** is a functor $C: \mathbf{R}_\infty^r \times \mathbb{R}_{\geq 0} \rightarrow \mathbf{R}_\infty^r$ such that for every $x \in \mathbf{R}_\infty^r$, $\tau, \varepsilon \in \mathbb{R}_{\geq 0}$:

- 1 $x \leq C(x, \varepsilon)$ and
- 2 $C(C(x, \varepsilon), \tau) \leq C(x, \varepsilon + \tau)$.

Example (Standard contour)

$C(x, \varepsilon) = x + \varepsilon \cdot v$, where $v = (v_1, \dots, v_r) \in \mathbb{R}_{\geq 0}^r$

ε -neighborhoods of 0

For $\varepsilon \in \mathbb{R}_{\geq 0}$ define

$$\mathcal{D}_\varepsilon := \{G \in \text{Tame}(\mathbb{R}_{\geq 0}^r, \text{Vect}_{\mathbb{K}}) \mid C(x, \varepsilon) \neq \infty \Rightarrow G(x \leq C(x, \varepsilon)) = 0\}.$$

Multigraded Betti numbers

Hilbert's syzygy theorem

Every f.g. \mathbb{N}^r -graded $\mathbb{K}[x_1, \dots, x_r]$ -module M has a minimal free resolution F_\bullet of length at most r , i.e., there exists an exact sequence of \mathbb{N}^r -graded modules

$$F_\bullet: F_r \xrightarrow{\delta_r} \cdots \longrightarrow F_0 \xrightarrow{\delta_0} M \longrightarrow 0,$$

such that the ranks of the F_i are simultaneously minimized.

Definition

The rank of F_i in a minimal free resolution of M as above is called the **i -th total multigraded Betti number** of M and is denoted by $\beta_i(M)$.

Computing $\widehat{\beta}_0 \dots$

- ◇ ... is NP-hard in general (Gäfvert–Chachólski, 2017)
- ◇ linear-time algorithm for quotients of monomial ideals in the bivariate case (Chachólski–Corbet–S., 2021)

A new invariant of multigraded modules

M a finitely generated \mathbb{N}^r -graded $\mathbb{K}[x_1, \dots, x_r]$ -module

Theorem & Definition (Chachólski–Corbet–S., 2021)

The hierarchical stabilization of β_0 w.r.t. the metric arising from the standard contour in the direction of $\mathbf{v} = (v_1, \dots, v_r) \in \mathbb{N}^r$ gives rise to

$$\dim_{\mathbf{v}}(M) = \min \{ \ell \mid \exists m_1, \dots, m_{\ell} \in M: x_1^{v_1} \cdots x_r^{v_r} \cdot M \subseteq \langle m_1, \dots, m_{\ell} \rangle \},$$

the **shift-dimension** of M . Such $\{m_1, \dots, m_{\ell}\}$ **v-generate** M and are a **v-basis** of M for $\ell = \dim_{\mathbf{v}}(M)$.

To be, or not to be in a \mathbf{v} -basis, that is the question.

An element $m \in M$ can be extended to a \mathbf{v} -basis of M if and only if

$$\dim_{\mathbf{v}}(M/\langle m \rangle) = \dim_{\mathbf{v}}(M) - 1.$$

Visualization

$$M = \langle x_1^3 x_2, x_1 x_2^3 \rangle / \langle x_1^4 x_2^4 \rangle \in \text{Mod}(\mathbb{K}[x_1, x_2]), \quad v = (1, 1) \in \mathbb{N}^2$$

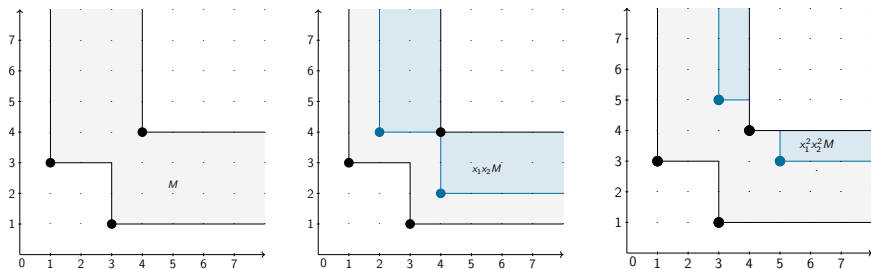


Figure: Visualization of M , $x_1 x_2 M$, and $x_1^2 x_2^2 M$

One reads:

- ◇ $M, x_1 x_2 M \subseteq \langle x_1^3 x_2, x_1 x_2^3 \rangle$, $x_1^2 x_2^2 M \subseteq \langle x_1^3 x_2^3 \rangle$, and $x_1^3 x_2^3 M = 0$.
- ◇ $\dim_{(0,0)}(M) = \dim_{(1,1)}(M) = 2$, $\dim_{(2,2)}(M) = 1$, and $\dim_{(3,3)}(M) = 0$.

Algebraic properties of the shift-dimension

Epimorphisms

If $\varphi: M \twoheadrightarrow N$, then $\dim_v(M) \geq \dim_v(N)$.

Proof: The image of a v -basis of M v -generates N .

Short exact sequences

Let $0 \rightarrow M \rightarrow L \rightarrow N \rightarrow 0$ be a short exact sequence of persistence modules. Then for all $v, w \in \mathbb{N}^r$, the following two inequalities hold:

- 1 $\dim_{v+w}(L) \leq \dim_v(M) + \dim_w(N)$,
- 2 $\dim_v(L) \leq \dim_v(N) + \beta_0(M)$.

Non-additivity

In general, $\dim_v(M \oplus N) \neq \dim_v(M) + \dim_v(N)$.

Outlook to future work

- ◇ extension of our algorithm
- ◇ application to data: which information does the shift-dimension reveal?
- ◇ construction of further multipersistence contours
- ◇ stabilization of invariants other than β_0

Thank your very much for your attention!

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